## **Sampling and Reconstruction**

The sampling and reconstruction process

- Real world: continuous
- Digital world: discrete

**Basic signal processing** 

- **■** Fourier transforms
- **■** The convolution theorem
- The sampling theorem

Aliasing and antialiasing

- **■** Uniform supersampling
- Nonuniform supersampling

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## Imagers = Signal Sampling

All imagers convert a continuous image to a discrete sampled image by integrating over the active "area" of a sensor.

$$R = \iiint_{t} \int \int L(x, \mathbf{w}, t) P(x) S(t) \cos \mathbf{q} \, dA d\mathbf{w} \, dt$$

**Examples:** 

■ Retina: photoreceptors

■ CCD array

**■ Vidicon: phosphors** 

Virtual "computer graphics" cameras do not integrate, instead they simply sample ...

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# **Displays = Signal Reconstruction**

All physical displays recreate a continuous image from a discrete sampled image by using a finite sized source of light for each pixel.

#### **Examples:**

■ DAC's: sample and hold

■ Cathode ray tube: phosphor spot and grid

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## **Sampling in Computer Graphics**

Artifacts due to sampling - Aliasing

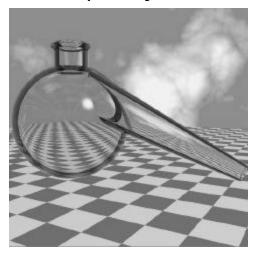
- Jaggies
- **■** Moire
- Flickering small objects
- Sparkling highlights
- Temporal strobing

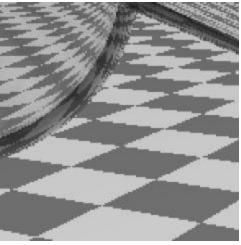
Preventing these artifacts - Antialiasing

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# **Jaggies**

#### **Retort sequence by Don Mitchell**





Staircase pattern or jaggies

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# **Spectral Analysis / Fourier Transforms**

Spectral representation treats the function as a weighted sum of sines and cosines

Each function has two representations

- Spatial (time) domain normal representation
- **■** Frequency domain spectral representation

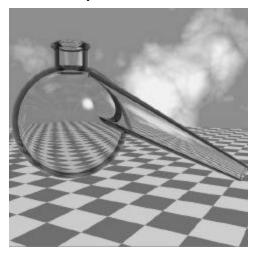
The Fourier transform converts between the spatial and frequency domain

Spatial Domain 
$$F(\mathbf{w}) = \int_{-\infty}^{\infty} f(x) e^{-i\mathbf{w}x} dx \implies f(x) = \frac{1}{2\mathbf{p}} \int_{-\infty}^{\infty} F(\mathbf{w}) e^{i\mathbf{w}x} d\mathbf{w} \iff \mathbf{F}$$
 Frequency Domain

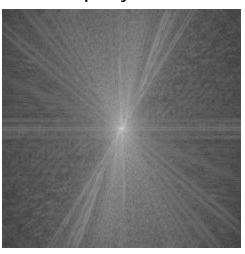
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# **Spatial and Frequency Domain**

**Spatial Domain** 



**Frequency Domain** 



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# Convolution

**Definition** 

$$h(x) = f \otimes g = \int f(x')g(x - x')dx'$$

Convolution Theorem: Multiplication in the frequency domain is equivalent to convolution in the space domain.

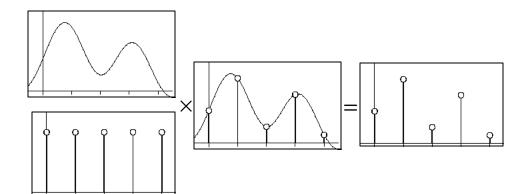
 $f \otimes g \leftrightarrow F \times G$ 

Symmetric Theorem: Multiplication in the space domain is equivalent to convolution in the frequency domain.

$$f \times g \leftrightarrow F \otimes G$$

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# **Sampling: Spatial Domain**

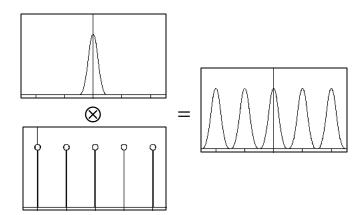


$$III(x) = \sum_{n=-\infty}^{n=\infty} \mathbf{d}(x - nT) \qquad f_s = \frac{1}{T} \quad \mathbf{w}_s = 2\mathbf{p}f_s = \frac{2\mathbf{p}}{T}$$

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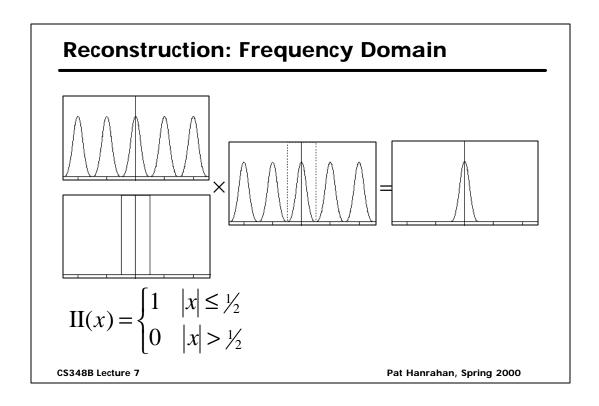
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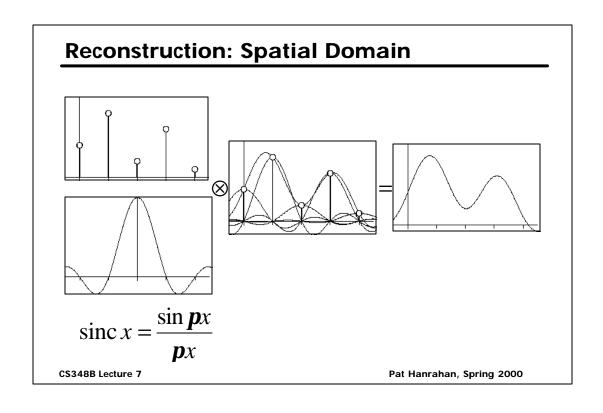
# **Sampling: Frequency Domain**

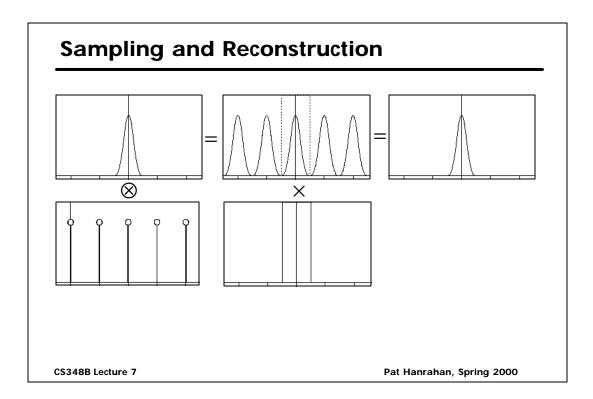


$$III(\mathbf{w}) = \sum_{n=-\infty}^{n=\infty} \mathbf{d}(\mathbf{w} - n\mathbf{w}_s)$$

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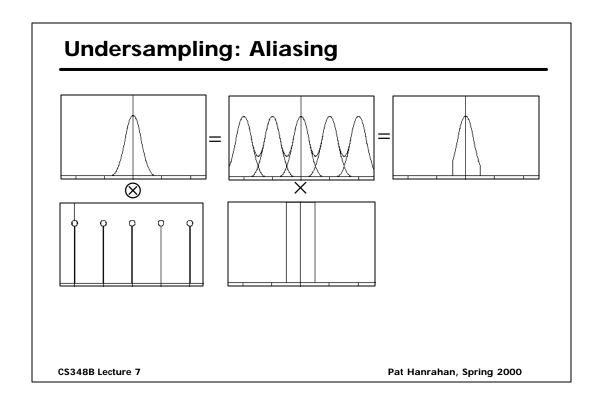
## **Sampling Theorem**

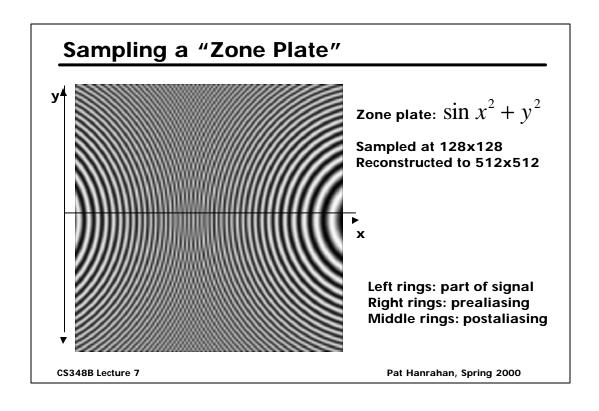
This result if known as the Sampling Theorem and is due to Claude Shannon who first discovered it in 1949

A signal can be reconstructed from its samples without loss of information, if the original signal has no frequencies above 1/2 the sampling frequency

For a given bandlimited function, the rate at which it must be sampled is called the Nyquist Frequency

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#### **Ideal Reconstruction**

Ideally, use a perfect low-pass filter - the sinc function - to bandlimit the sampled signal and thus remove all copies of the spectra introduced by sampling

#### Unfortunately,

- The sinc has infinite extent and we must use simpler filters with finite extents. Physical processes in particular do not reconstruct with sincs
- The sinc may introduce ringing which are perceptually objectionable

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## **Mitchell Cubic Filter**

$$h(x) = \frac{1}{6} \begin{cases} (12 - 9B - 6C)x^3 + (-18 + 12B + 6C)x^2 + (6 - 2B) & |x| < 1 \\ (-B - 6C)x^3 + (6B + 30C)x^2 + (-12B - 48C)x + (8B + 24C) & 1 < |x| < 2 \\ 0 & otherwise \end{cases}$$

**Properties:** 

$$\sum_{n=-\infty}^{n=\infty} h(x) = 1$$

B - spline: (1,0)

Catmull - Rom : (0,1/2)

From Mitchell and Netravali Look at other figures in that paper

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## **Aliasing and Antialiasing**

If the scene contains frequencies greater than the Nyquist Frequency, then we have a aliasing problem

#### Results of aliasing:

- Jaggies
- **■** Moire
- **■** Flickering small objects
- Sparkling highlights
- **■** Temporal strobing

#### Preventing aliasing or antialiasing:

- 1. Analytically prefilter the signal
- 2. Uniform supersampling and resample
- 3. Nonuniform or stochastic sampling

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# 

## **Antialiasing by Prefiltering**

Ideally, low-pass with a perfect filter (a sinc function) to bandlimit the function to the Nyquist sampling rate.

Unfortunately, the sinc has infinite extent and we must use simpler filters (like a box filter, or area average).

#### Practically:

- **■** Constant colored polygonal fragments doable
- **■** Complex environments not doable

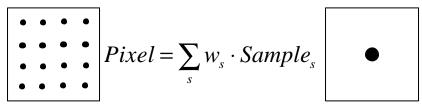
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### **Uniform Supersampling**

Increasing the sampling rate moves each copy of the spectra further apart, potentially reducing the overlap and thus aliasing

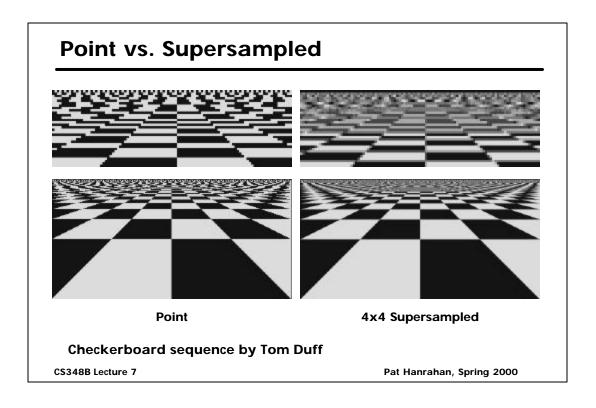
Resulting samples must be resampled (filtered) to image sampling rate

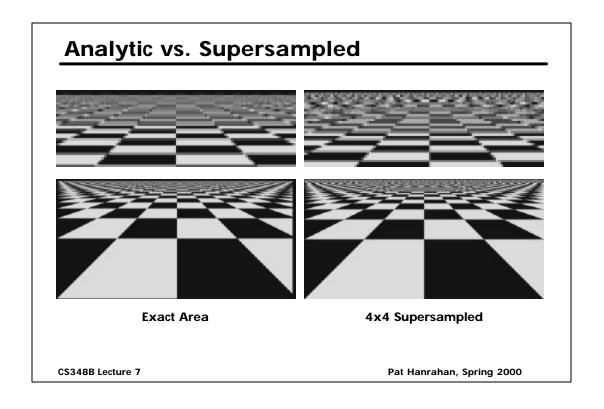


Samples

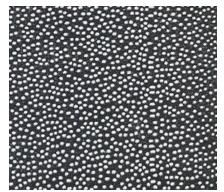
Pixel

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#### **Distribution of Extrafoveal Cones**







**Fourier transform** 

#### Yellot theory

- Aliases replaced by noise
- Visual system less sensitive to high frequency noise

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## **Non-uniform Sampling**

#### Intuition

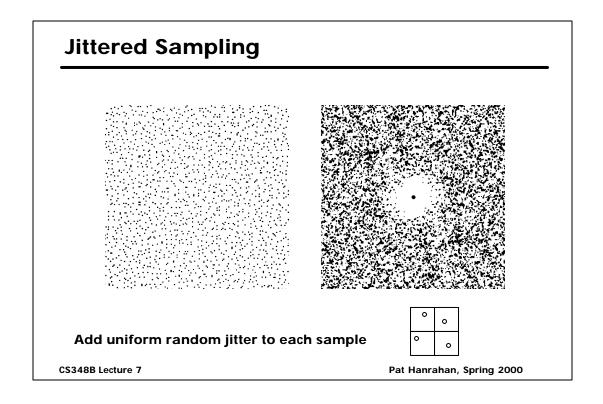
#### **Uniform sampling**

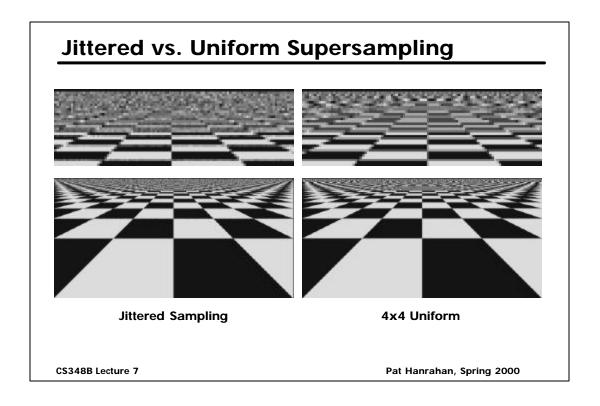
- The spectrum of uniformly spaced samples is also a set of uniformly spaced spikes
- Multiplying the signal by the sampling pattern corresponds to placing a copy of the spectrum at each spike (in freq. space)
- Aliases are coherent, and very noticable

#### Non-uniform sampling

- Samples at non-uniform locations have a different spectrum; a single spike plus noise
- Sampling a signal in this way converts aliases into broadband noise
- Noise is incoherent, and much less objectionable

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# **Analysis of Jitter**

#### Non-uniform sampling

$$s(x) = \sum_{n=-\infty}^{\infty} d(x - x_n)$$

$$x_n = nT + j_n$$

#### Jittered sampling

$$j_n \sim j(x)$$

$$j(x) = \begin{cases} 1 & |x| \le 1/2 \\ 0 & |x| > 1/2 \end{cases}$$

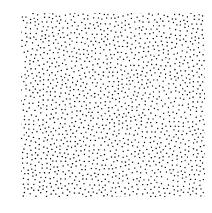
$$J(\mathbf{w}) = \operatorname{sinc} \mathbf{w}$$

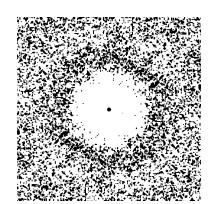
$$S(\mathbf{w}) = \frac{1}{T} \left[ 1 - \left| J(\mathbf{w}) \right|^2 \right] + \frac{2\mathbf{p}}{T^2} \left| J(\mathbf{w}) \right|^2 \sum_{n = -\infty}^{n = -\infty} \mathbf{d} \left( \mathbf{w} - \frac{2\mathbf{p}n}{T} \right)$$
$$= \frac{1}{T} \left[ 1 - \operatorname{sinc}^2 \mathbf{w} \right] + \mathbf{d} \left( \mathbf{w} \right)$$

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## **Poisson Disk Sampling**





Dart throwing algorithm

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# **Filtering Nonuniform Samples**

1. Reconstruction

$$P = \frac{\sum_{s} w(x_s, y_s) \cdot S(x_s, y_s)}{\sum_{s} w(x_s, y_s)}$$

Note: For jittered samples may approximate with filter coefficients at centers of each cell

- 2. Filtering further attenuates high frequency noise
- 3. Problematical if samples are clumpy

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