## Appendix A

## Properties of the Representation Matrices

In this appendix, we derive the two properties of representation matrices listed in equation 2.35 . The first property follows from the addition theorem for spherical harmonics (see for instance, Jackson [34] equation 3.62),

$$
\begin{equation*}
Y_{l 0}(u, v)=\Lambda_{l} \sum_{m=-l}^{l} Y_{l m}^{*}(\theta, \phi) Y_{l m}\left(\theta^{\prime}, \phi^{\prime}\right) \tag{A.1}
\end{equation*}
$$

Here, $v$ is a dummy-variable since $Y_{l 0}$ has no azimuthal dependence, and $u$ is the angle between $(\theta, \phi)$ and $\left(\theta^{\prime}, \phi^{\prime}\right)$, i.e.

$$
\begin{equation*}
\cos u=\cos \theta \cos \theta^{\prime}+\sin \theta \sin \theta^{\prime} \cos \left(\phi-\phi^{\prime}\right) \tag{A.2}
\end{equation*}
$$

Now, let $(u, v)=R_{\alpha}\left(\theta^{\prime}, \phi^{\prime}\right)$. Here, $R_{\alpha}=R_{y}(\alpha)$. We omit the $z$ rotation since that does not affect $Y_{l 0}$ which has no azimuthal dependence. The vector corresponding to coordinates $(u, v)$ is then given by

$$
\left(\begin{array}{c}
\sin u \cos v  \tag{A.3}\\
\sin u \sin v \\
\cos u
\end{array}\right)=\left(\begin{array}{ccc}
\cos \alpha & 0 & \sin \alpha \\
0 & 1 & 0 \\
-\sin \alpha & 0 & \cos \alpha
\end{array}\right)\left(\begin{array}{c}
\sin \theta^{\prime} \cos \phi^{\prime} \\
\sin \theta^{\prime} \sin \phi^{\prime} \\
\cos \theta^{\prime}
\end{array}\right)=\left(\begin{array}{c}
\cos \alpha \sin \theta^{\prime} \cos \phi^{\prime}+\sin \alpha \cos \theta^{\prime} \\
\sin \theta^{\prime} \sin \phi^{\prime} \\
\cos \alpha \cos \theta^{\prime}+\sin \alpha \sin \theta^{\prime}\left(-\cos \phi^{\prime}\right)
\end{array}\right)
$$

Since $\left(-\cos \phi^{\prime}\right)=\cos \left(\pi-\phi^{\prime}\right)$, we know from equation A. 2 that $u$ corresponds to the angle between $(\alpha, \pi)$ and $\left(\theta^{\prime}, \phi^{\prime}\right)$. In other words, we may set $\left.\theta, \phi\right)=(\alpha, \pi)$. To summarize,

$$
\begin{equation*}
Y_{l 0}\left(R_{\alpha}\left(\theta^{\prime}, \phi^{\prime}\right)\right)=\Lambda_{l} \sum_{m=-l}^{l} Y_{l m}^{*}(\alpha, \pi) Y_{l m}\left(\theta^{\prime}, \phi^{\prime}\right) . \tag{A.4}
\end{equation*}
$$

To proceed further, we write the rotation formula for spherical harmonics, omitting the $z$ rotation by $\beta$, since that has no significance for azimuthally symmetric harmonics.

$$
\begin{equation*}
Y_{l 0}\left(R_{\alpha}\left(\theta^{\prime}, \phi^{\prime}\right)\right)=\sum_{m=-l}^{l} d_{0 m}^{l}(\alpha) Y_{l m}\left(\theta^{\prime}, \phi^{\prime}\right) \tag{A.5}
\end{equation*}
$$

A comparision of equations A. 4 and A. 5 yields the first property of representation matrices in equation 2.35 , i.e.

$$
\begin{equation*}
d_{0 m}^{l}(\alpha)=\Lambda_{l} Y_{l m}^{*}(\alpha, \pi) \tag{A.6}
\end{equation*}
$$

To obtain the second property in equation 2.35 , we use the form of the spherical harmonic expansion when the elevation angle is 0 , i.e. we are at the north pole. Specifically, we note that $Y_{l m^{\prime}}\left(0^{\prime}, \phi^{\prime}\right)=\Lambda_{l}^{-1} \delta_{m^{\prime} 0}$. With this in mind, the derivation is as follows,

$$
\begin{align*}
Y_{l m}(\alpha, \beta) & =Y_{l m}\left(R_{\alpha, \beta, \gamma}\left(0^{\prime}, \phi^{\prime}\right)\right) \\
& =\sum_{m^{\prime}=-l}^{l} D_{m m^{\prime}}^{l}(\alpha, \beta, \gamma) Y_{l m^{\prime}}\left(0^{\prime}, \phi^{\prime}\right) \\
& =\Lambda_{l}^{-1} D_{m 0}^{l}(\alpha, \beta, \gamma) \tag{A.7}
\end{align*}
$$

This brings us to the second property stated in equation 2.35 ,

$$
\begin{equation*}
D_{m 0}^{l}(\alpha, \beta, \gamma)=\Lambda_{l} Y_{l m}(\alpha, \beta) \tag{A.8}
\end{equation*}
$$

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